

## Math 304 Linear Algebra

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## Highlights

**Reminder.** The first examination is Friday, June 9.

From last time:

- ▶ A set of vectors is linearly independent if none of the vectors is in the span of the others.
- ▶ A set of vectors is linearly dependent if some non-trivial linear combination of the vectors equals the  $\mathbf{0}$  vector.

Today:

- ▶ the notions of basis and dimension
- ▶ changing coordinates

## Basis

A *basis* for a vector space is:

- ▶ a linearly independent set of vectors that spans the vector space
- ▶ equivalently, a maximal linearly independent set of vectors
- ▶ equivalently, a minimal spanning set for the vector space

**Example.** The *standard basis* for  $R^3$  consists of the three

vectors  $\mathbf{e}_1 = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}$ ,  $\mathbf{e}_2 = \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}$ , and  $\mathbf{e}_3 = \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}$ .

One nonstandard basis for  $R^3$  consists of the three vectors

$\mathbf{v}_1 = \begin{pmatrix} 1 \\ 2 \\ 3 \end{pmatrix}$ ,  $\mathbf{v}_2 = \begin{pmatrix} 4 \\ 5 \\ 6 \end{pmatrix}$ , and  $\mathbf{v}_3 = \begin{pmatrix} 7 \\ 8 \\ 0 \end{pmatrix}$ .

## Example: exercise 10 on page 151

Extract a basis for  $R^3$  from the following vectors:

$$\mathbf{x}_1 = \begin{pmatrix} 1 \\ 2 \\ 2 \end{pmatrix}, \quad \mathbf{x}_2 = \begin{pmatrix} 2 \\ 5 \\ 4 \end{pmatrix}, \quad \mathbf{x}_3 = \begin{pmatrix} 1 \\ 3 \\ 2 \end{pmatrix}, \quad \mathbf{x}_4 = \begin{pmatrix} 2 \\ 7 \\ 4 \end{pmatrix}, \quad \mathbf{x}_5 = \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix}$$

**Solution.** The vectors  $\mathbf{x}_1$  and  $\mathbf{x}_2$  are linearly independent, but they do not form a basis for  $R^3$  because they do not span  $R^3$ . The vectors  $\mathbf{x}_1$ ,  $\mathbf{x}_2$ , and  $\mathbf{x}_3$  do not form a basis because they are linearly dependent ( $\mathbf{x}_3 = \mathbf{x}_2 - \mathbf{x}_1$ ). Vectors  $\mathbf{x}_1$ ,  $\mathbf{x}_2$ , and  $\mathbf{x}_4$  do not form a basis because they are linearly dependent:

$$\det \begin{pmatrix} 1 & 2 & 2 \\ 2 & 5 & 7 \\ 2 & 4 & 4 \end{pmatrix} = 0. \quad \text{However, } \det \begin{pmatrix} 1 & 2 & 1 \\ 2 & 5 & 1 \\ 2 & 4 & 0 \end{pmatrix} = -2 \neq 0, \text{ so}$$

vectors  $\mathbf{x}_1$ ,  $\mathbf{x}_2$ , and  $\mathbf{x}_5$  do form a basis for  $R^3$ .

## Dimension

The *dimension* of a vector space is the number of vectors in a basis. (All bases of a vector space have the same number of vectors.)

### Examples.

- ▶ The dimension of  $R^3$  equals 3.
- ▶ The dimension of the space  $R^{2 \times 5}$  of  $2 \times 5$  matrices equals 10.
- ▶ The dimension of the space  $P_3$  of polynomials of degree less than 3 equals 3. (One basis is  $1, x, x^2$ .)
- ▶ The function space  $C[0, 1]$  is infinite dimensional. (Any finite subset of the functions  $1, x, x^2, x^3, \dots$  is linearly independent.)

## Example continued

Consider another nonstandard basis  $\mathbf{v}_1 = \begin{pmatrix} 5 \\ 6 \end{pmatrix}$ ,  $\mathbf{v}_2 = \begin{pmatrix} 4 \\ 5 \end{pmatrix}$ .

How are coordinates with respect to the  $\mathbf{u}$  basis related to coordinates with respect to the  $\mathbf{v}$  basis?

The matrix  $\begin{pmatrix} 5 & 4 \\ 6 & 5 \end{pmatrix}$  whose columns are  $\mathbf{v}_1$  and  $\mathbf{v}_2$  transforms  $\mathbf{v}$  coordinates to standard coordinates, and the inverse matrix  $\begin{pmatrix} 5 & -4 \\ -6 & 5 \end{pmatrix}$  transforms from standard coordinates to

$\mathbf{v}$  coordinates. Since  $\begin{pmatrix} 1 & -1 \\ 1 & 1 \end{pmatrix}$  transforms from  $\mathbf{u}$  coordinates to standard coordinates, the product matrix

$$\begin{pmatrix} 5 & -4 \\ -6 & 5 \end{pmatrix} \begin{pmatrix} 1 & -1 \\ 1 & 1 \end{pmatrix} = \begin{pmatrix} 1 & -9 \\ -1 & 11 \end{pmatrix}$$

transforms from  $\mathbf{u}$  coordinates to  $\mathbf{v}$  coordinates.

So the  $\mathbf{v}$  coordinates of  $\mathbf{x}$  are  $\begin{pmatrix} 1 & -9 \\ -1 & 11 \end{pmatrix} \begin{pmatrix} 4 \\ -1 \end{pmatrix}_{\mathbf{u}} = \begin{pmatrix} 13 \\ -15 \end{pmatrix}_{\mathbf{v}}$ .

## Change of basis: an example

Let  $\mathbf{u}_1 = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$  and  $\mathbf{u}_2 = \begin{pmatrix} -1 \\ 1 \end{pmatrix}$  be a nonstandard basis for  $R^2$ ,

and let  $\mathbf{e}_1$  and  $\mathbf{e}_2$  be the standard basis vectors. Let  $\mathbf{x} = \begin{pmatrix} 5 \\ 3 \end{pmatrix}$ .

Then  $\mathbf{x} = 5\mathbf{e}_1 + 3\mathbf{e}_2$ . In other words, 5 and 3 are the *coordinates* of the vector  $\mathbf{x}$  with respect to the standard basis. Since  $\mathbf{x} = 4\mathbf{u}_1 - \mathbf{u}_2$ , the coordinates of  $\mathbf{x}$  with respect to the  $\mathbf{u}$  basis are 4 and  $-1$ .

**Question.** How are the  $\mathbf{u}$  coordinates and the standard coordinates related?

$$\begin{pmatrix} 5 \\ 3 \end{pmatrix}_{\mathbf{e}} = \mathbf{x} = 4\mathbf{u}_1 - \mathbf{u}_2 = \begin{pmatrix} 1 & -1 \\ 1 & 1 \end{pmatrix} \begin{pmatrix} 4 \\ -1 \end{pmatrix}_{\mathbf{u}}$$

The *transition matrix* between  $\mathbf{u}$  coordinates and standard coordinates is the matrix whose columns are the standard coordinates of the  $\mathbf{u}$  basis vectors. The inverse matrix gives the change from standard coordinates to  $\mathbf{u}$  coordinates.